# CatLog Gen2 - GPS/GNSS Data Logger

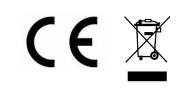
# **User Manual**







Revision: March 16, 2021



# CatLog Gen2 GPS/GNSS Logger Perthold Engineering LLC

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#### 1. Introduction

#### 1.1 Important Facts to save you Trouble

Important facts to know about your CatLog GPS device. Read this to prevent device damage and avoid low performance.



**Delivery state of battery**: The battery is only charged to about 25-40%. Do not expect to get the full operation time without charging the battery!

**Discharged battery**: Never store devices with discharged batteries. The battery will get permanently damaged.

**Charge battery in cold climate**: Never charge a battery at freezing temperatures! Minimum charge temperature is 5 deg C / 40 Fahrenheit.

**Battery temperature:** Especially for sealing ThermSeal devices there is a chance to overheat the device battery. Rule of thumb: If you can not touch it - it is too hot! If it is too hot the battery will die soon afterwards.

**GPS Database**: In order to get a quick, energy efficient GPS position the receiver internal database needs to be up to date. In the delivery state the database is not up –to-date. Enable Option "GPS database acquisition" before charging the battery or press button "Activate GPS" once sufficiently charged.

**GPS Antenna**: The antenna needs to stay dry to efficiently receive GPS signals. If you apply textile tape to your GPS make sure it does not cover the antenna because tape can collect moisture leading to signal attenuation.

**Software and Device Driver**: Install the Software beforehand to identify trouble before you are in the field. For the installation it is not required to have devices. The software is available for free on your support page of the website.

#### 1.2 CatLog Features



Used in thousands of GPS tags around the world CatLog became the standard GPS data recorder for wildlife bio-tagging. The device will record the position in an adjustable time interval. The movement profile can later be displayed on a map or exported to use with other software.

Generation 2 of the CatLog has been specifically optimized for scientific use while still maintaining an excellent performance to cost balance.

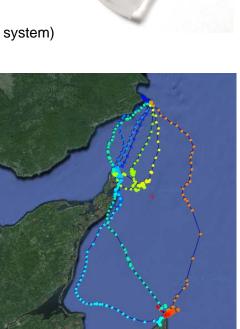
Its low power consumption combined with small dimensions, low weight and high accuracy makes it an ideal device for domestic and wildlife animal observation.

Optimized for scientific use, CatLog offers the following features:

- Magnetic switch to activate and deactivate it
- Choice of different enclosures to withstand seawater and tough conditions
- Optimized weight and operation time by scalable battery size
- Lots of configuration options to get the best results for your project needs.
- Retrieval option
- Advanced scheduler (dual time table)
- Ready for alternative energy supply (self containing system)

The recorded data is stored in an open text format that can be used by most 3<sup>rd</sup> party programs.

However, CatLog has also its own visualization software. This allows the user to analyze the recorded data as well as to apply multi-level filters or export only certain portions of the whole data set. It also allows visualizing position accuracy estimates which is one specific feature of the Gen2 CatLog.





#### **1.3 Specifications**

Specifications like size, weight, runtime can be found in the datasheet "CatLog Gen2 – Data Sheet" located on our website:

<u>www.mr-lee.com</u>  $\rightarrow$  Science Line  $\rightarrow$  Support  $\rightarrow$  Manuals & Instructions

Since the device can be customized to the customer requirements the version you have may not be reflected by the general data sheet.

#### 1.4 Support and Help

You can get in contact with the technical support by sending a mail to engineering@perthold.de

Website: www.mr-lee.com

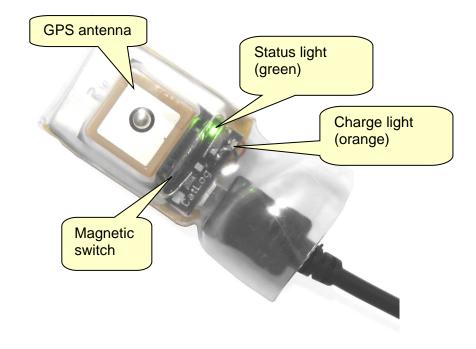
#### 2. Device Hardware

#### 2.1 Device Overview

The CatLog GPS recorder has a very compact size and can come in different enclosures and battery configurations. Towards the end of this manual is a description of enclosure specific features. However, functional elements are the same and described below.

If the device is equipped with a ceramic patch antenna (as shown in below picture) or chip antenna care must be taken that it faces up into the sky for optimal performance. Wire antennas will have no orientation requirements.

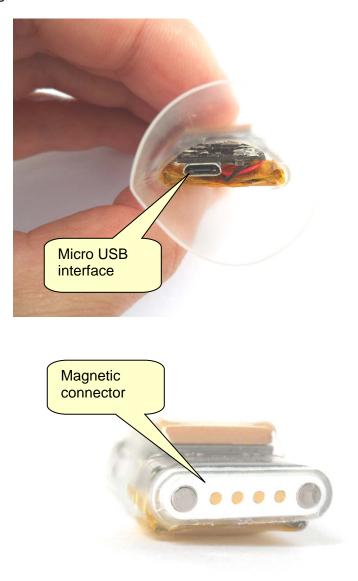
There are 3 control / status elements on the device: a switch to turn it on and off, 2 lights to inform about the operation status.



The lights will show you the status:

Status	Green light	Orange light
Battery charging	-	On
Device connected to	On	-
computer		
Device connected, acquiring	-	On
position		
Device is switched on	Flashes rapidly for 1s	-
Device is switched off	On for about 2s	-
Device enabled	Blinks every 8s	-
Device is acquiring position	-	Blinks every 8s (depends on
		HW version)
Device is storing position	Flashes quickly 2 times	Flashes 2 times (depends on
		HW version)
Battery empty	Flashes slowly 2 times	-

The device interface is usually either a Micro USB port or a waterproof magnetic connector and is used for charging and communication with the computer, see images below. See section "Charge and Communicate" for more details.



Some device versions have different interface connectors. Especially devices potted in Epoxy resin will feature a special connector that has some critical points that need to be considered. Please see section "Enclosure Variants" for important information.

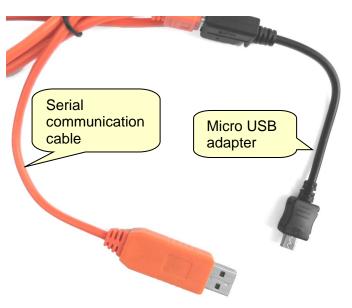
#### 2.2 Charge and Communicate

Depending on the device connector version a matching USB cable is required. This is usually supplied with your devices. It needs to be noted that there are cables for charging only and cables that are used for both charging and communicating.

Charging will start automatically when the cable is plugged in a power source and connected to the device. The charge light (orange) will turn on while the battery is charged and turn off when the battery is fully charged.

**<u>Note</u>**: Do not store the device with a discharged battery. The battery will get permanently damaged.

To communicate with the device a special cable is required. It interfaces the serial interface of the GPS to the computers USB port. A software driver needs to be installed (see section USB cable driver). Below is a picture of the serial communication cable with a Micro USB adapter.



Normally the device turns automatically on once the connection to the computer has been made. If not, then you will need to turn ON the device manually in order to establish communication after connecting it to the USB interface.

If the popular feature "No turning off once enabled" is set, then you need to connect the device to the cable, turn it manually OFF, wait 10 seconds and then turn it manually ON to establish communication.

In some cases (e.g. battery completely drained) and depending on battery capacity it may take some minutes to reach a charge level that allows the device to operate.

As soon as the device is connected to an USB port the battery will be charged. If the device is OFF or in operation mode no charge indicator will be visible.

#### 2.3 Switch Device On and Off

CatLog GPS is equipped either with a magnetic switch or a push button. In case of a push button simply press the button.

If your device has a magnetic switch then take a permanent magnet and place it in the proximity of the switch (see Device Overview, location can vary). The switching zone is left or right of the center. To get familiar with the switching zones and correct distance simply swipe the magnet across the switch. **Please do not touch the switch directly with a magnet!** If the magnet seems not to work then change the polarity of it.

The green light will come on immediately after the switch is activated. But the device will turn ON only after the switch is closed for a longer duration. This will be signaled with a rapid flashing of the green status light.

#### 3. Software Setup

The latest version of the software is always available from the Mr. Lee website (<u>www.mr-lee.com</u>  $\rightarrow$  Science Line  $\rightarrow$  Support). Software is only available for Windows operation systems.

The software package contains the CatLog GPS Control Center and drivers. Unpack the zip file in a dedicated directory. Start SETUP.EXE.

Before you can start the Control Center and work with the device two drivers need to be installed:

- a) Driver for the USB cable (PL2303)
- b) In some cases (if not covered by the SETUP program): Driver for serial communication (SCOMM32)

The following sections will give you more details about this.

#### 3.1 USB Cable Driver

#### Note: Normally installed with setup program. Skip this section.

The PL2303 USB cable driver installation depends on the operation system you are using. If you are unsure, open the computers Control Panel, Click on System. System Information panel will open; look at section System, System Type.

Once you know if you have 32 or 64bit OS when open the folder "PL2303\_driver" of the CatLog Control installation package.

#### All Windows 64 bit operating systems including Windows 10:

- 1. Unplug all USB-To-Serial adapters
- 2. Double click on the installer "PL2303\_64bit\_Installer.exe"
- 3. When it prompts you, plug in one (1) of your USB-To-Serial adapters and click "Continue".
- 4. Reboot your computer

#### All Windows 32 bit operating systems from XP up:

- 1. Unplug all USB-To-Serial adapters
- 2. Run the installer program "PL-2303\_Driver\_Installer.exe".
- 3. If it offers a choice to remove the driver, then select to remove the current driver. Then run the installer again to install the correct driver.
- 4. Reboot your computer

#### **3.2 Serial Communication Driver**

#### Note: Normally installed with setup program. Skip this section.

Installation procedure of SCOMM32.OCX (Serial Communication Driver) depends on the operation system.

Step 1: Copy the ocx into windows system folder.

- a) Windows 32 bit: to c:\windows\system32 (requires Admin rights)
- b) Windows 64 bit: to c:\windows\syswow64 (requires Admin rights)

Step 2: Open command prompt

- a) Windows 7 or Vista:
  - Select Start > All Programs > Accessories
  - Right-click on "Command Prompt" in the Accessories
  - Click "Run as Administrator"
- b) Windows 8:
  - Open the "Quick Link" menu (by holding down the Windows 8 logo key and pressing the X key)
  - Select "Command Prompt (Admin)"
  - Select "Yes" to allow changes
- c) Windows XP: skip this step

#### Step 3: Register OCX

- a) 32bit Windows Version: enter the following string in command prompt: c:\windows\system32\regsvr32 c:\windows\system32\SComm32.ocx
- b) 64bit Windows Version: enter the following string in command prompt: c:\windows\syswow64\regsvr32 c:\windows\syswow64\SComm32.ocx
- c) Windows XP: In versions of Windows prior to Vista, or with User Account Control (UAC) turned off in Windows Vista, 7, or 8, ActiveX files (such as .dll or .ocx) can be registered by double-clicking on the filename in Windows Explorer ("File Explorer" in Windows 8). If opening, running, or double-clicking on a file with a .dll extension (Dynamic Link Library) or an .ocx extension (OLE Control Extension) brings up an "Open With" screen: click "Select the program from a List" and click OK > click the "Browse" (or "Other") button on the lower right of the screen > progressively select directories and change the "Look-in" box on the next screen to C:\Windows\System32\regsvr32.exe > double-click on regsvr32.exe (or click the Open button) > verify that "Microsoft Register Server" is highlighted in the Programs list > verify that a check mark is in the "Always Use" box on the lower left of the Open With screen > click the OK button on the "Open With" screen. A message should appear indicating that the registration succeeded. Click the OK button on the RegSvr32 message screen.

#### 4. Control Center

The CatLog GPS Control Center will be your main tool to work with the GPS device. It is used to configure the functionality and read the recorded data.

We tried to minimize efforts when working with multiple devices. Therefore the configuration can be done without having an actual device connected. That way settings can be applied to all devices with a minimum number of steps.

Below an overview of the main screen.

		Connection to device	
🚾 CatLog GPS Control C	enter		
Connect	COM 16 💌 Refresh	HW n/a SW n/a Device Name CatLog	Serial Device Configuration
GPS Activate			
Read Data Erase Data	Capture Interval Time A/Main 60 sec Capture Interval Time B 300 sec GPS Timeout 90 seconds	Scheduler Settings UTC Su Mo Tu We Th 00 A A A A A 01 A A A A A	
Read Settings Write Settings	Keep receiver alive  Auto Off Number of positions before log	00       A       A       A       A         01       A       A       A       A       A         02       A       A       A       A       A         03       A       A       A       A       A         04       A       A       A       A       A         05       A       A       A       A       A         06       A       A       A       A       A         07       A       A       A       A       A         08       A       A       A       A       A         10       A       A       A       A       A         11       A       A       A       A       A         12       A       A       A       A       A       A         13       A       A       A       A       A       A       A         19       A       A       A       A       A       A       A         20       A       A       A       A       A       A       A       A         21       A       A       A       <	
Settings to File	2nd chance after     Seconds delay		
Settings from File	<ul> <li>Disable GPS for</li> <li>Log also if no position</li> </ul>	08 A A A A A 09 A A A A A A 10 A A A A A A 11 A A A A A A	
Batch Mode	Log additional: C Temp	11 A A A A A A A A A A A A A A A A A A	
Setup Center	No Turning OFF once enabled	14 A A A A A A A	
Battery Simulator	<ul> <li>LED lights disabled</li> <li>3D Lock required</li> </ul>	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	
Exit	Synchronous Mode  Synchronous Mode  Advanced Syncmode	18     A     A     A       19     A     A     A       20     A     A     A       21     A     A     A	
	Speed triggered interval		
User actions	if speed > 20 knots then use interval 8 se	ec 23 A A A A A A A A A A A A A A A A A A	
	Delayed start from date: 12 h 4 d 6 m 18 Stop recording after: 13 h 4 d 6 m 18 Recovery from date: 14 h 4 d 6 m 18	3 y 3 y	
	Recovery interval 60 sec Check T		Advanced

#### 4.1 Connecting GPS Device

Step 1: Plug in PL2303 serial communication USB cable, Click "Refresh", Select COM port (usually highest one). This step only needs to be done once per session.

Step 2: Connect device to USB cable. Check if green light turns on and stays on. If not activate switch so that device turns on (green light stays on).

Step 3: Click "Connect". Heartbeat indicator should turn red, buttons in the action section should be enabled after some seconds, device information (hardware, software, serial) should be updated.

#### 4.2 Disconnecting GPS Device

The former "Connect" Button turned into "Disconnect". Once you are done with the device, click "Disconnect". You can now unplug the device from the USB cable. If you plan to work with other devices do not remove the USB cable from the computer. You can simply plug the USB cable into the next device. Continue with Step 2 of Section "Connecting USB Device".

#### 4.3 Device Configuration

You will find that you can already make changes to the device configuration without having a device actually connected. This concept allows to configure multiple devices with just a few clicks.

You can either press the "Read Settings" button to read the settings of the connected device or do the editing without the actual device settings.

Press "Write Settings" to deploy the settings to one or more devices (after disconnecting and connecting following devices).

The CatLog GPS device is highly customizable. Please refer to the following sections that explain the different operation modes and options.

#### 4.3.1 Operation Modes

The device supports 2 different operation modes:

- Standard Interval Mode
- Weekly Scheduled Mode

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#### 4.3.1.1 Standard Interval Mode

Use this mode if energy conservation is not the primary concern.

This mode wakes the device periodically and takes a position. The time is defined by "Capture Interval Time A / Main". The interval is not synchronized, meaning it is free running.

Capture Interval Time A/Main	60	sec
Capture Interval Time B	300	sec

### 4.3.1.2 Weekly Scheduled Mode

This mode allows conserving energy by tailoring the operation time.

Based on a weekly calendar the GPS device can be enabled for certain hours a day or certain days a week. This option will make the system acquire the GPS date and time to synchronize the operation.

When the GPS is enabled by the scheduler it will use the "Capture Interval Time A" or "Capture Interval Time B" to log positions, depending on the settings in the scheduler matrix.

The example to the right will use Interval time A from 00:00 to 00:59, Interval time B from 01:00 to 02:59 and disables the device from 03:00 to 04:59.

	Su	Mo
00	A	A
01	В	В
02	В	В
03	•	•
04	•	•

Care must be taken that the capture interval time is shorter than the available time window defined in the scheduler (e.g. time window set to 1 to 2 o'clock = 1 hour, capture time interval needs to be smaller for example 45min).

**Note:** the GPS time is UTC time, all settings in the scheduler will use UTC time and not local time. You need to adjust the scheduler based on your local time if required.

#### 4.3.2 Options for Accuracy and Energy Consumption

This section will explain you the options responsible to balance between accuracy and energy consumption. It will try to make the relations transparent so that you can decide what settings are the right ones for your case.

#### 4.3.2.1 GPS Timeout

The GPS receiver requires some time depending on reception conditions to acquire the current position. Under some circumstances the GPS receiver may take a long time to get a position, e.g. when device is under water. Since the receiver will operate in the highest power state to scan the GPS satellite signals the battery will drain significantly.

To prevent this the time to get a valid position can be limited. This is set using the **GPS Timeout**. This time should not be shorter than 60s because this option can limit the receiver to a point there no position at all can be acquired keeping the GPS device in an unproductive endless loop.

#### 4.3.2.2 When no position available

If reception conditions are unfavorable and the GPS device can not get a valid position within the GPS Timeout time the device can be configured perform different actions:

When no position available:				
2nd chance after	0	seconds delay		
Disable GPS for	0	seconds		
🔲 Log also if no position				

- a) to try it a second time. This is especially useful if the main Capture Interval time is long and the GPS device would only log a few positions every day. To have such kind of backup, enable option "2nd chance when no position". Now the time defined by this option will enable the GPS device allowing the system to gather a position outside the regular capture interval.
- b) to turn the GPS device OFF ("blackout") for the specified time. The assumption is that unfavorable reception conditions will persist for a while so energy is wasted if the GPS tries over and over again to get a position. So the GPS is simply disabled and energy is conserved until the GPS turns back ON after the specified time is over.
- c) To log an invalid position with timestamp

#### 4.3.2.3 3D Position Lock required

Once the GPS device is receiving valid signals and is able to determine the current position several options are available to increase the accuracy of the position. In general terms, the longer the GPS receiver is enabled the better the position will get but the more energy is required.

One option to significantly increase the accuracy is to select "**3D Lock required**". For this 3 dimensional position at least 4 different satellites are required. For a "simple" 2D position only 3 satellites are required. The GPS receiver usually starts searching for one satellite, reads the date and time and then searches for possible other satellites based on a predicted constellation. So the normal sequence is 2D lock and if more satellites are received 3D lock and then switch to tracking the satellites with the best signal.

#### 4.3.2.4 Number of Positions before Logging

An other option for accuracy improvement is to increase the "**Number of Positions before log**". Once the minimum number of satellites (see 2D/3D lock) is met the GPS device will count the number of valid positions until the position is recorded. This allows the GPS receiver to find enough satellites to improve the calculation of the current position. When only a few positions per day or week are taken it is advised that this number is increased. It will keep the GPS enabled for a longer period allowing to find enough satellites. Default value is 0, each unit will keep the device enabled for approx.. 1 additional second. This may drain the battery significantly.

#### 4.3.3 Additional Options

**Device name**: allows to assign each device a specific name. This comes handy if multiple devices are used. Identification is also the serial number of the device. It is unique for every device and cannot be changed.

**No turning OFF once enabled**: This options prevents the device from being switched OFF once it is switched ON. The device will need to be connected to the control program and the option disabled before it can operate in the conventional way. Preventing the device from getting switched off is useful for situations were either there is a danger of accidentally switching the device off (e.g. vibrations during operation) or disabling the device on purpose is prevented (stealth observation). Note: if this option is enabled the device will turn OFF after disconnecting from the computer, you need to turn it ON for use.

Please see Section "Charge and Communicate" for how to disable this option.

**LED lights disabled**: Enabling this option will disable the LED lights once the device is in operation mode. LED lights will still be visible during enabling, disabling and charge & communication. This option will save energy as well as will prevent disturbances while in operation.

**Speed triggered Interval:** Depending on the speed the device moves the position logging interval can be adjusted. Set speed threshold at which the device will switch to the specified interval time. Please note: Speed detection only happens while a position is taken. If no position is taken but the device moves fast it will not trigger this feature.

**Delayed start:** This option will switch the device ON at a certain hour of a specific date. Until this date the device is in off-state and conserving energy. You do not need to manually switch the device ON for activating this function. If the device is turned ON manually this option has no effect.

**Stop recording:** if set the device will stop GPS recording after the given date/time. This allows to conserve battery energy for retrieval features.

**Recovery**: This option will stop regular device operation at a certain date. The device will go into recovery mode and conduct a recovery action (e.g. flashing LED) in the specified action interval. This option will override the "LED off" option.

**Synchronous Mode**: In normal operation the GPS will acquire a position, go back to sleep for the time defined by the capture interval and then acquire the next position. That means the time required to acquire the position (usually some seconds) is not taken into account and will cause an undefined drift of the logging time points. For certain applications such as having multiple devices synchronized this option will try to mitigate the time required for position acquisition. The Synchronous Mode option is best used with the Scheduler since this will guarantee that every GPS device is using the same satellite time.

Advanced Syncmode: While the regular Sync Mode only adjusts the logging interval based on the time required for acquiring the previous position the Advanced Syncmode forces the device to take the position at the absolute time. This is more energy demanding, however, it allows to synchronize multiple devices to one point in time.

#### 4.4 Read Recorded Data

Click on "Read Data" to read the stored position data of the connected GPS device. A dialog will open to choose a file name and output format. The following formats are supported:

- CSV Excel text table
- TXT Text format (contains additional information, e.g. reasons for shutdowns, battery voltage, ...)
- GPX interchangeable format

Additional setting for output formats can be made with the Button "Setup Center" located on the main window:

Setup		
Save Data:	☐ Add Device N	ame to Filename erial to Filename
Datafield separator:	💿 Comma	🔿 Semikolon
Extract Data:	C Position only	Position + Status Info
Date Format:	• mm/dd/yy	C yy-mm-dd

Data is then be read from the device and decompressed. Depending on the amount of positions this will take a significant time. Since the device is using so called circular memory architecture it will not immediately recognize the end of the data stream. Therefore a stop button is present. If you see no increase of the position numbers for some seconds you can stop the download.

#### 4.4.1 GPS Data Explanation

Depending on the version and configuration the device records the following data:

- Date and Time: UTC Satellite date and time
- Latitude, Longitude: Position coordinates
- Altitude: Height above mean sea level in meters
- Satellites: Number of visible/received satellites
- HDOP, PDOP: Horizontal dilution of precision / Position dilution of precision ; number for geometrical accuracy of the position
- Temperature: device temperature in deg C
- Speed: GPS speed of device in km/h.
- TTFF: Time it took to get the position from starting the GPS to getting the position fix. A high number tells you that the reception situation was problematic, it gives also an indicator for battery usage (longer time = more energy used).
- SNR AVG, SNR MAX: SNR stands for signal to noise ratio in dB. Recorded are the maximum SNR from the best satellite received and the average of all satellites currently received.

#### 4.5 Erase Device Memory

To erase the data memory, press "Erase Data". For safety purpose a dialog will ask you if you are sure. Depending on the memory size the erase process will last for a while.

**Important:** erased data can not be restored.

#### 4.6 Batch Processing

With multiple devices being configured or read the process can get tedious. For this the Batch Processing feature has been added. It will work through a defined task list for every connected device. You simply need to connect the device to the cable and press the start button. When it will go from top to bottom of the action list that may contain Connect/disconnect, read data, erase data, write settings. The example below will read data from the device and if that was successfully completed erase the memory. Data format and output folder is set one time by pressing "Set Folder" button.

Execution will stop in case of errors.

Batch Mode	
Select actions for batch processing, bottom, Execution will stop in case of error,	Execution order is from top to
🔽 Connect	
🔽 Read Data	Set Folder
🔽 Erase Data	
Write Settings	🔽 Keep Device Specifics
Disconnect	
Start	Cancel

#### 4.7 Hints for Best Battery Lifetime

There a two main points to consider for improving the operation time / battery life:

- disabling LED lights
- Allow the GPS to build internal database

**Disabling the LED status lights** will significantly improve battery life for long term operation, especially when the GPS logger will only record a few positions per day. In such a case battery draining by the status lights will become significant. As a rough number the status lights will consume about 2000mAh in energy per year.

**GPS Database**. The GPS receiver has an internal database of satellite positions. This database is built from information sent by satellites. The better the database is filled the quicker the position is acquired and the lower the energy consumption. The collected data will expire quickly. Having an up to date database right from the start will significantly reduce the power consumption of your device. In order to achieve this press the button "GPS activate" and take the device outside. It will enable the GPS engine for about half an hour and then will switch off itself. It is advised to recharge the device after this procedure.

### 5. Enclosure and Interface Variants

There is a choice of different enclosures to accommodate the projects needs. The following section will explain specific details of different enclosure types.

### 5.1 ThermoSeal™

One key feature of the CatLog GPS is the ThermoSeal enclosure that offers the best environmental protection for the least weight. It is a special heat shrink tubing with outstanding characteristics.



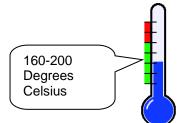
ThermoSeal<sup>™</sup> Features:

- Provides reliable water tightness and is absolutely corrosion and pressure resistant.
- Reusable seal, just heat it up to open it and seal it again with heat !
- Sufficient wall thickness to mechanically protect the device
- Sticks to tape for universal deployment
- Allows to create special attachment fixtures
- Cheap, clean, economic, simple !

#### 5.1.1 Sealing Process

Below follows the description of the sealing process. We have also a video available to show the workflow and details.

The ThermoSeal material is handled like regular shrink tubing. You will need the following tools: Heat gun, seal clamp and scissors. All CatLog-S devices are pre-sealed and just need to be sealed on the interface prior to use. We sell the sealing tool as well as the ThermoSeal material. Please note that regular shrink tubing will not have the ability to open and close the seal again without compromising the seal tightness. Before you start adjust the sealing clamp. Adjust With the adjustment wheel you set the clamp clamp force. Make the adjustments while pressure the clamp is open, when close the clamp to see the resulting gap size/pressure. The clamp will lock itself in closed position making it very convenient for the later sealing operation. To unlock press the handle lever as indicated in the picture below. Unlock clamp The right adjustment for ThermoSeal is that in closed empty position the jaws still touch each other but the closing pressure is very low.

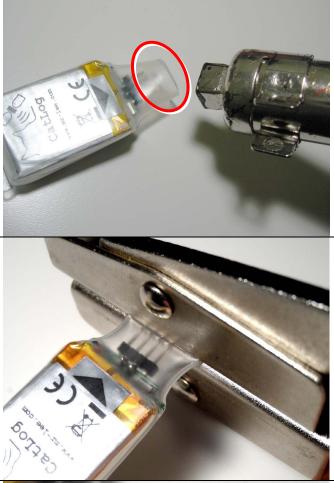


Next step is to adjust the heatgun. The optimal temperature range is 160-200 degrees Celsius (320 – 390 Fahrenheit). If you have an unregulated heatgun you will need to vary the distance between air outlet and device to not overheat the material. You may also want to shield the battery. The battery may get damaged by too high temperatures.

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Now heat the material at the sealing location (see red circle in image) from **all sides** until it gets soft and sticky. If you are opening a seal apply heat until the material gets back to the tubular shape. Do not overheat or apply heat for a long period of time. Usually it takes 30s to 1 minute to properly heat the material.

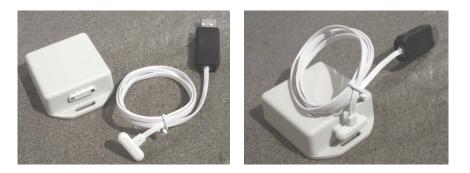
Now quickly take the device, place the seal area between the jaws (center area) and close the clamp. It is important to note to **not clamp parts of the device**.



After about 30-60s you can unlock the clamp and remove the device. In batch operation you will heat the next device while the seal of the previous device cools down. Please remember to let the clamp cool down itself from time to time.

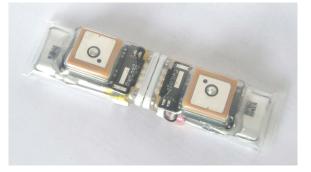
If the seal is closed for the first time you may need the scissors to cut off excess material. The ideal seal width is 5-8mm.

#### **5.2 Magnetic Connector**



Some devices are equipped with waterproof magnetic interface connectors. There are some things to consider with this interface type:

- Do not force the cable side of the connector in reverse position onto the device side. The connector should "snap" into place by itself.
- Before you make contact be sure the device connector is **perfectly** clean.
- Make sure that the magnets of the connector do not influence with the magnetic switch of the device. If possible, snap 2 devices together for transportation.



• Care must also be taken to not short the cable connector on a metallic surface. The attached power supply or your computer may be damaged.

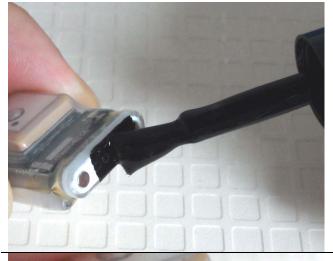


Since the contacts need to stay clean to allow good connection, but the devices are used in the field there is a solution for this contradicting situation. For devices which are deployed with exposed interface we supply a so called peel-off protective paint. The procedure to apply and remove this paint is explained below.

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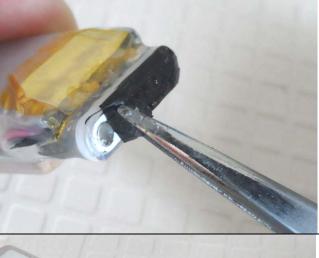


Shake bottle well before use. Take small brush and apply a layer of paint over the connector.



The paint shall be tried in about 1 hour. It is recommended to apply a second paint layer for easier removal of the paint. If the paint layer is too thin it may get difficult to remove it in one piece. Once the paint is dry, the device is ready to get deployed.

To remove the paint layer, start in one corner to peel it off the surface using your finger nails. Once a larger portion is loose use tweezers or fingers to pull it slowly off.



Ideally the whole paint layer comes finally off in once piece. If not, use a second paint layer next time. The interface is perfectly clean and allows a good electrical contact.



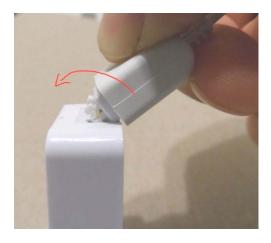
#### **5.3 Epoxy Potted Devices**

Devices potted in epoxy feature an extreme water pressure resistance, abrasion and piercing resistance.



Other than devices in ThermoSeal, which are hermetically sealed, Potted devices have their interface exposed to the environment. This requires a different type of connector.

The cables are not plugged in straight to the devices. They are also not allowed to get pulled out straight. Take a look at the following photo. The plug is set in an angular position, then pressed into the device and moved up. For removing the cable the plug is bent down until the connector disengages. Pulling the cable straight out will damage both the connector as well as the plug



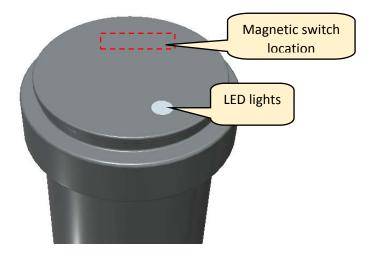
Even though the connector is Gold plated you need to protect the interface against corrosion especially if you are going to use it in salt water. Some use wax or dip-in-rubber. A coat of latex color, applied only to the terminals would be an alternative choice, this can be removed with rubbing alcohol.

#### 5.4 Tubular Enclosure

This enclosure is made from impact resistant plastic. It has a cap on each end hold by an internal gasket ring. This makes the enclosure water and air tight. One cap contains the GPS receiver.



There are several versions of the enclosure: with air purge hole and without. With the receiver integrated in the cap and standalone receiver. With magnetic switch and with manual switch. Latest version shown below.



Devices with air purge hole have a cap with a screw on the side opposite to the GPS receiver. This is the air purge hole and needs to be open while opening or closing the enclosure. Otherwise air pressure in the enclosure will either prevent removing a cap or the cap cannot reliable closed.

Devices without air purge have special caps that are very hard to get removed by hand. A special tool is required. Below are the instructions to open the device with such caps.

of the tool.

First, locate the cap with the larger diameter, it will cover the GPS unit.

Take the tool and place the cap in one half of the tool.

Place the cap also in the second half

Put your fist around the tool and slightly pull in lateral direction to lose the cap a bit to get more grip with the tool clamps.

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Firmly pull the tool in a straight line from the enclosure. It will pull out the cap.

Skip if pull-tool was used.

Otherwise, remove the screw from purge opening

Skip if pull-tool was used.

Remove cap from opposite end by "wiggling" it out.



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GPS can now get accessed and connected to USB communication cable (note: for communication a special cable is required)

The GPS can get disconnected from battery to charge the battery with high current charger.

To reassemble:

Place GPS in cap, antenna facing to the outside, put in foam spacer to hold GPS in place.

Arrange battery cable in a circular manner so that cap can get pushed in all the way

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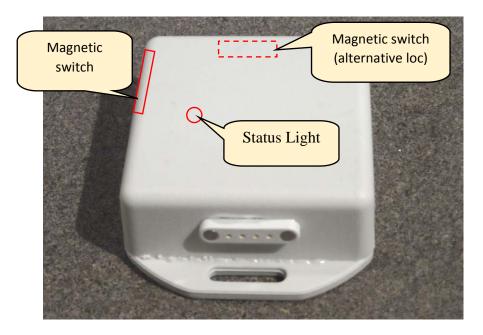
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To attach the enclosure to a collar or harness two hose clamps can be used.

#### 5.5 Sealed Box

The CatLog Gen2 GPS engine is integrated in a hermetically sealed plastic enclosure. The GPS device is by default equipped with status lights and magnetic switch for manual operation, however, due to the nature of the plastic box this may not visible on first sight. See picture below where these elements are located in relation to the interface connector. It is advised to have the device in a dark environment to see the lights shining through the plastic. Furthermore, if devices need to be enabled in the field where status light can not be seen, it is recommended to use the automatic start function.



Please read also the section about magnetic interface connector.

#### 6. GPS Data Viewer

The GPS Data Viewer is a standalone program. The latest version of it is also available from the Mr. Lee website (<u>www.mr-lee.com</u>  $\rightarrow$  Science Line  $\rightarrow$  Support).

For visualization and data analysis of recorded GPS data the GPS Data Viewer offers a lot of features while trying to stay as easy as possible.

The viewer can utilize both Google and Bing maps (see configuration). It requires an active internet connection.

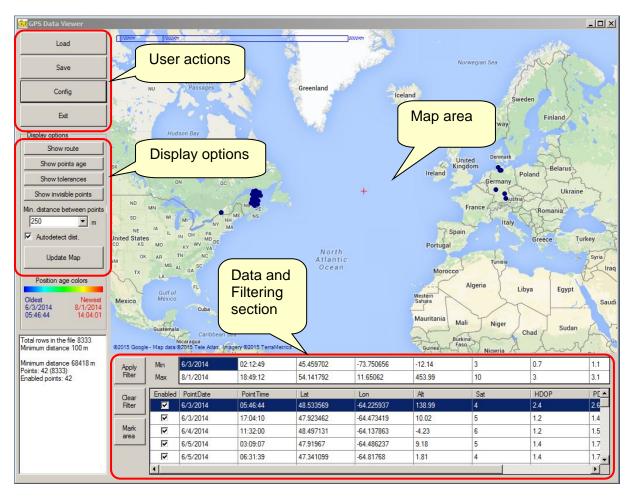
The following sections will guide you through the features.

#### 6.1 Installation

Download and unzip the program. No installation is required.

#### 6.2 Overview

Below you can see the main screen of the viewer. Controls are arranged in specific sections as indicated.



#### 6.2.1 Map Area

The map area shows data points according to filtering and display options. The following controls are available:

- Zoom-in: Rotate mouse wheel forward
- Zoom-out: Rotate mouse wheel backward
- Move map: Hold right mouse button and move mouse
- Select area of data points: Hold Shift key, left click mouse button and move mouse pointer. See more details in Filtering section.

#### 6.2.2 User Actions

**Load**: here you select the GPS data file (CSV format) which was saved by CatLog Control Center to visualize.

Save: Writes data to CSV file. Only data points passing all filter criteria are saved.

Config: Opens a configuration window. Following options are present:

- Maps: Choose between Google Maps and Bing Maps
- View: Selects the map style (Satellite images, graphical map or hybrid view)
- Dot size: small or regular dots for data point display
- Route (connection between data points) color and width
- Maximum number of points: defines the maximum number of data points that will be displayed with all features. Since all data points need to be uploaded to the map service this will considerably slow down the program. If the filter settings result in a data point count exceeding this number certain display features will be disabled.

#### 6.2.3 Data Filtering

Once a dataset is loaded all positions will be displayed on the map and you will get a table with all data points below the map screen.

With an increasing number of data points you may wish to reduce the number of relevant points. Also for certain analysis procedures it might be important to look only at data points with certain characteristics.

You can basically apply two different types of filter criteria:

- Numerical filter: filter criteria is set in the data table
- Spatial filter: filter criteria is set on the map

Both filtering types can be combined. The following section will explain each type in more detail.

Once a filter criteria is set or changed, it will only become effective if the Button "Apply Filter" is pressed.

To remove all filter criteria (both numerical and spatial) press the button "Clear Filter".

#### 6.2.3.1 Numerical Filtering

All available data points are listed in the data table. For each column a filter range can be defined. Initially the filter min/max values will show the lowest and highest value present in the current data set. If you click into each min/max field you can change the upper or lower limit for each column. Only data points that are in between the minimum and the maximum value will pass the filter.

So for example you want to remove all data points with bad reception conditions. Columns HDOP and/or Tolerance would need to be filtered. Click in field HDOP min, select 0. Click in field HDOP max, select 2. Click button "Apply Filter". Now only data points with an HDOP value of 0 to 2 will remain.

Min	.750656	-12.14	3	0	1.1	2.1
Max	650 <mark>6</mark> 2	453.99	10	2	3.1	9
Enabled	<u>ժ</u> ի	Alt	Sat	HDOP	PDOP	Tolerance
	225922	136.17	3	1.8	2.1	5.4
2	473419	10.02	5	1.2	1.4	3.6
V	137863	-4.23	6	1.2	1.5	3.6
	186237	9 19	5	1/	17	12

Additionally every data point can be manually disabled by removing the check mark in column "Enabled".

Short overview of available data columns other than position and date:

**Sat**: Number of satellites present for this data point. The higher the more accurate **HDOP**: Horizontal dilution of precision: Quality indicator of position (2D): The lower the more accurate

**PDOP**: Position dilution of precision: Quality indicator of position (3D): The lower the more accurate

**Tolerance**: Estimated tolerance radius of position in meters; derived from quality indicators. The lower the better.

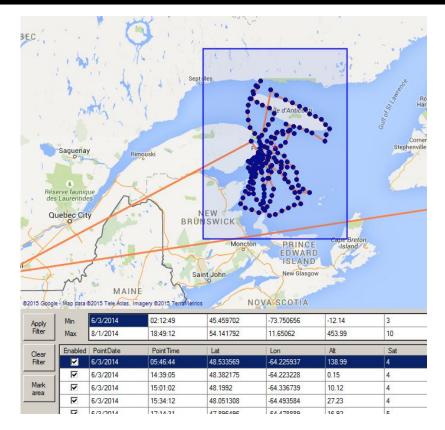
#### 6.2.3.2 Spatial Filtering

Spatial filtering applies to data points on the map. An area is selected that contains data points of interest. All data points not in the area are filtered out.

To apply a spatial filter you have two ways. One is to press button "Mark area" and then move the mouse pointer to one corner of the area, right click the mouse and drag the pointer to the other corner of the area. The other way is to hold the Shift key while doing the same.

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The spatial filter becomes effective after the button "Apply Filter" is pressed. To remove the area selection simply right click on the map.

The status window on the lower left hand side will show you how many data points remain after setting the filter.

Another kind of spatial filter is sitting in the display options. The "minimum distance between points" limits the number of data points on the map based on the map scale. For example if you have to zoom level set to 0 (whole world view) two positions that are 10 meters from each other are not possible to be displayed as two separate dots and can be represented by just one dot.

	between points
8121	▼ m
Autodetec	t dist.
Update	e Map

The value of minimum distance tells the program that all points with a distance lower than the defined value will be filtered out. The value can be selected manually or automatically based on the map scale. Button "Update Map" needs to be pressed each time the value was changed manually or the map was zoomed in/out.

To reset all spatial filters select a value 0 for "minimum distance between points", disable "autodetect", press button "update map, "press the button "Clear Filter".

#### 6.2.4 Display Options

There are certain options to change the display of data points. Note that some features are only feasible if the number of data points is below the **Maximum number of points** defined in the configuration. The current number of data points passing all filter criteria is visible in the status window on the lower left hand corner.

Show route: connects data points with a line

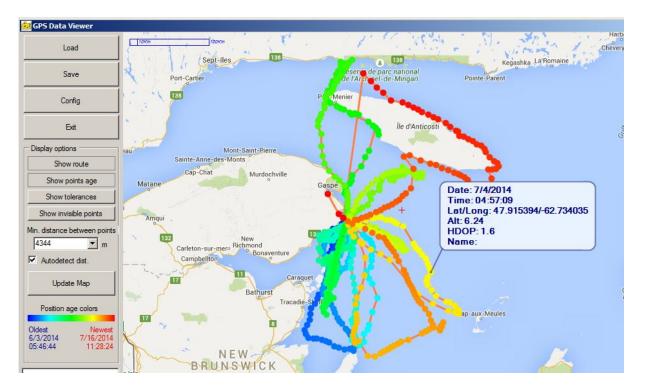
**Show points age**: Color codes each data point based on the date and time. Oldest position is dark blue, newest position is red. This simplifies the understanding of more complex movement profiles.

**Show tolerance**: Shows a tolerance circle for each position. Only useful with highest zoom level. See explanation of "Tolerance" column for details.

**Show invisible points**: displays points that are not passing filter criteria as an "X". **Minimum distance between points**: see spatial filters

Changes become only effective after pressing the button "Update Map".

See also "Configuration" options for how to change colors and sizes of data points and lines.



Summary of each data point is shown if you move the mouse pointer on it.